

BOUT:
Boundary Turbulence Simulations Code
in Magnetic Fusion Devices

X.Q.Xu

Lawrence Livermore National Laboratory
University of California
Livermore, CA 94550, USA



Presented at
BlueGene/L workshop
August 13-14, 2002
Lake Tahoe, CA, USA

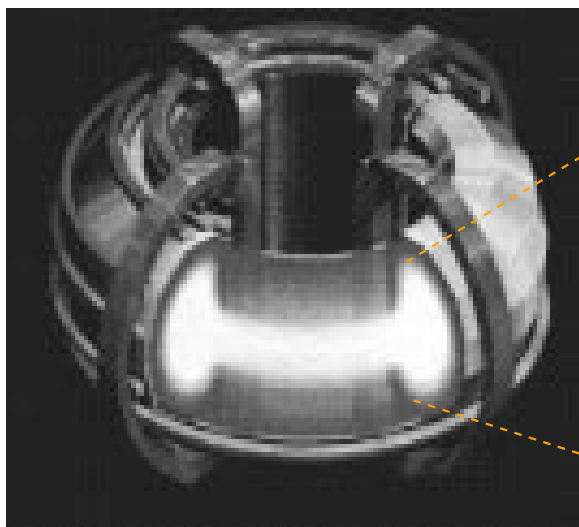
BOUT Developer Team and Their Quest



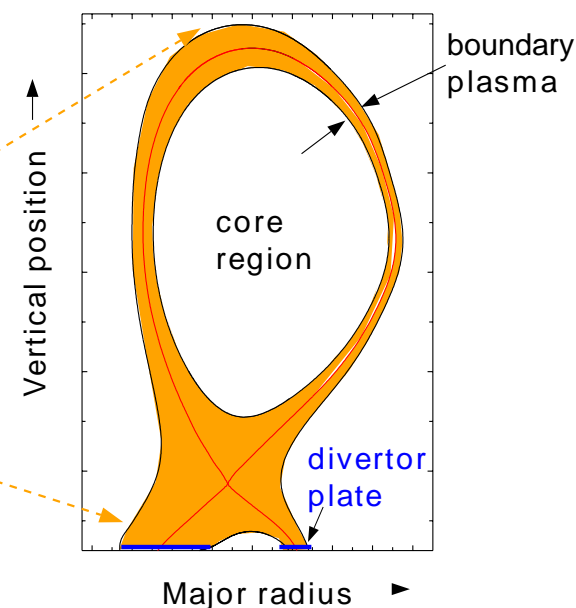
Ron Cohen	LLNL
Bill Meyer	LLNL
Bill Nevins	LLNL
Tom Rognlien	LLNL
Marv Rensink	LLNL
Xueqiao Xu	LLNL
D. Ulrich	CSUS

Phil. Snyder	GA
Sergei Galkin	UCSD
S. Krashenninikov	UCSD
Jim Myra	Lodestar Inc.
Ralf Kleiber	IPP/Germany
P. Catto/A. Simakov	MIT

Tokamak magnetic fusion device

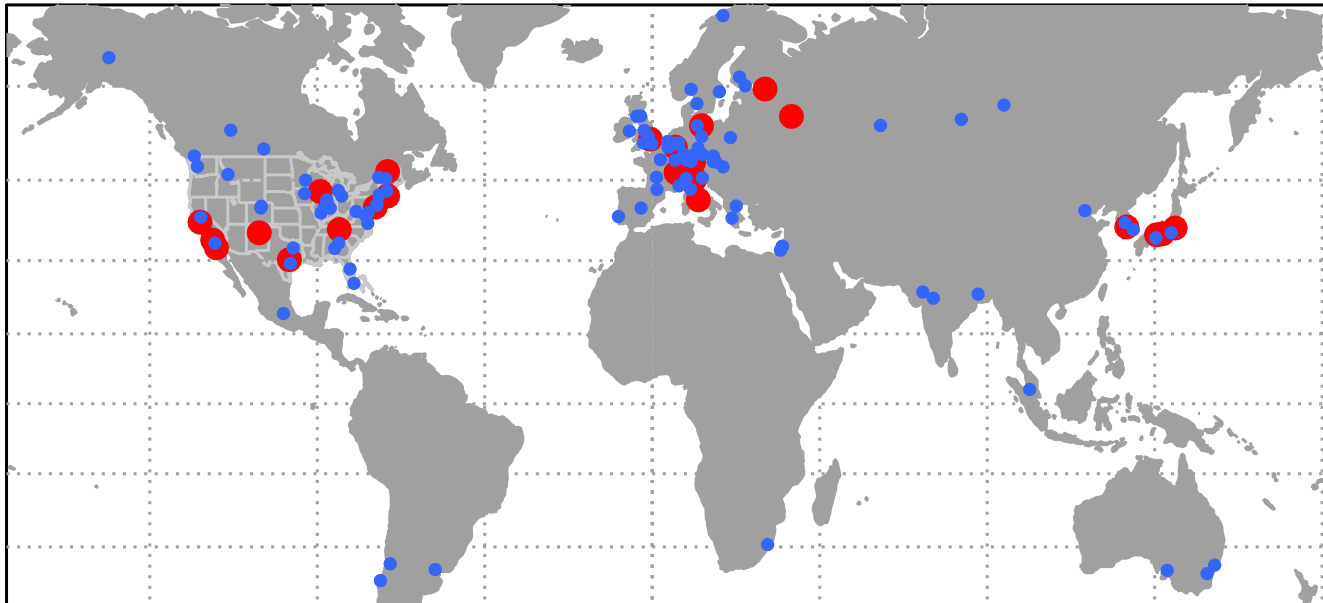


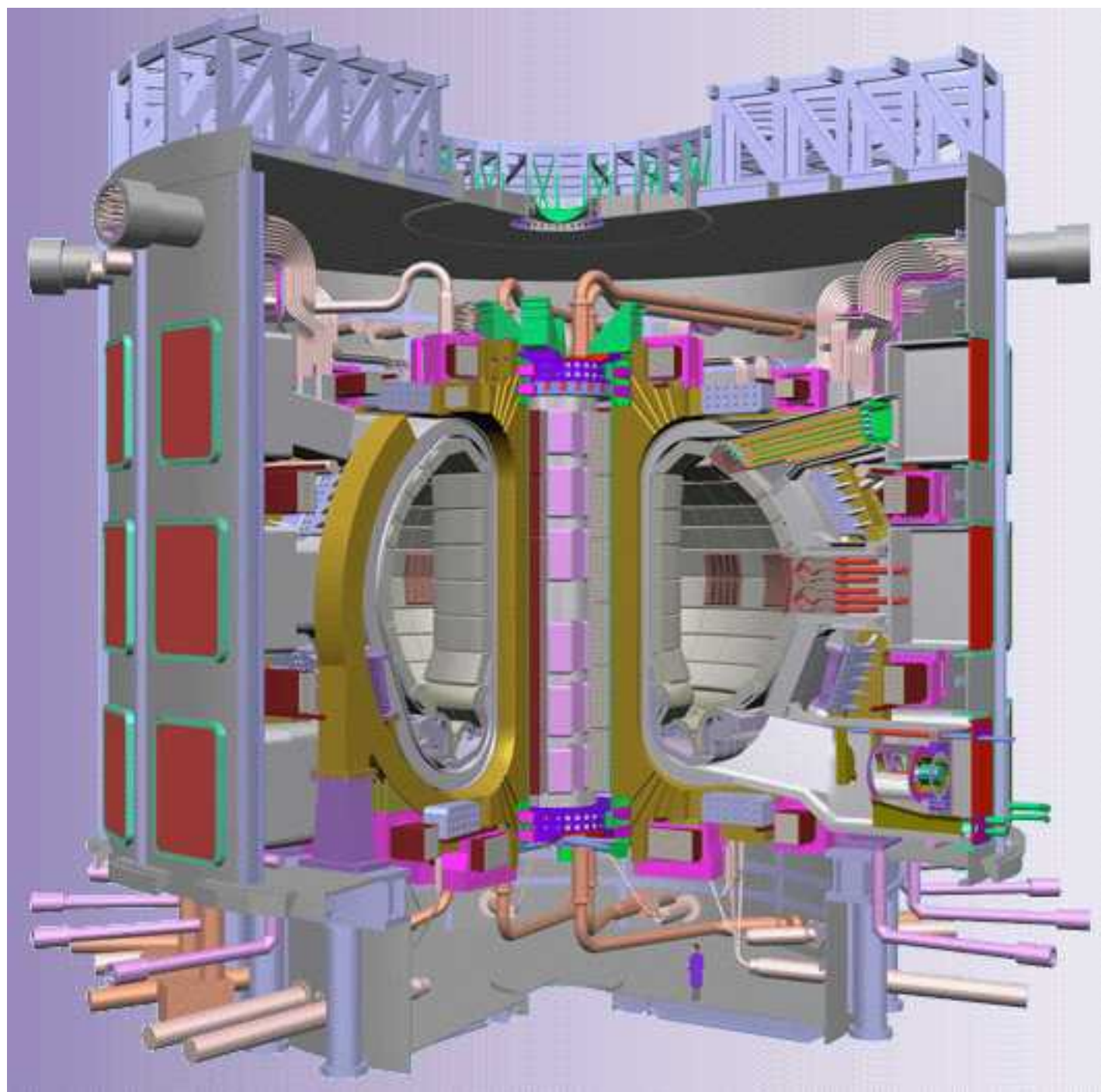
Simulated boundary-plasma region



SCOPE OF THE WORLD FUSION PROGRAM

- At last count - 33 countries, 180 institutions (67 in the US)
- Emphasis Varies
 - US priority to science mission for now, US has withdrawn from burning plasma project - ITER
 - EU, Japan give priority to energy mission





FACILITIES AND INFRASTRUCTURE ARE EXTENSIVE

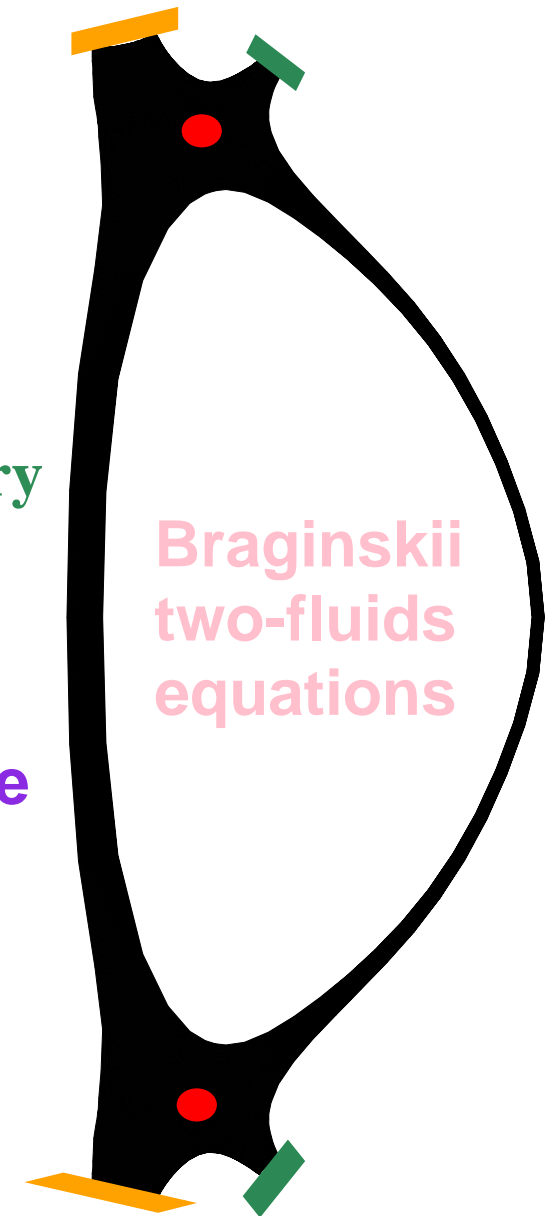


© 1995 JET Joint Undertaking - All Right Reserved

BOUT is 3D EM Boundary Plasma Turbulence Code



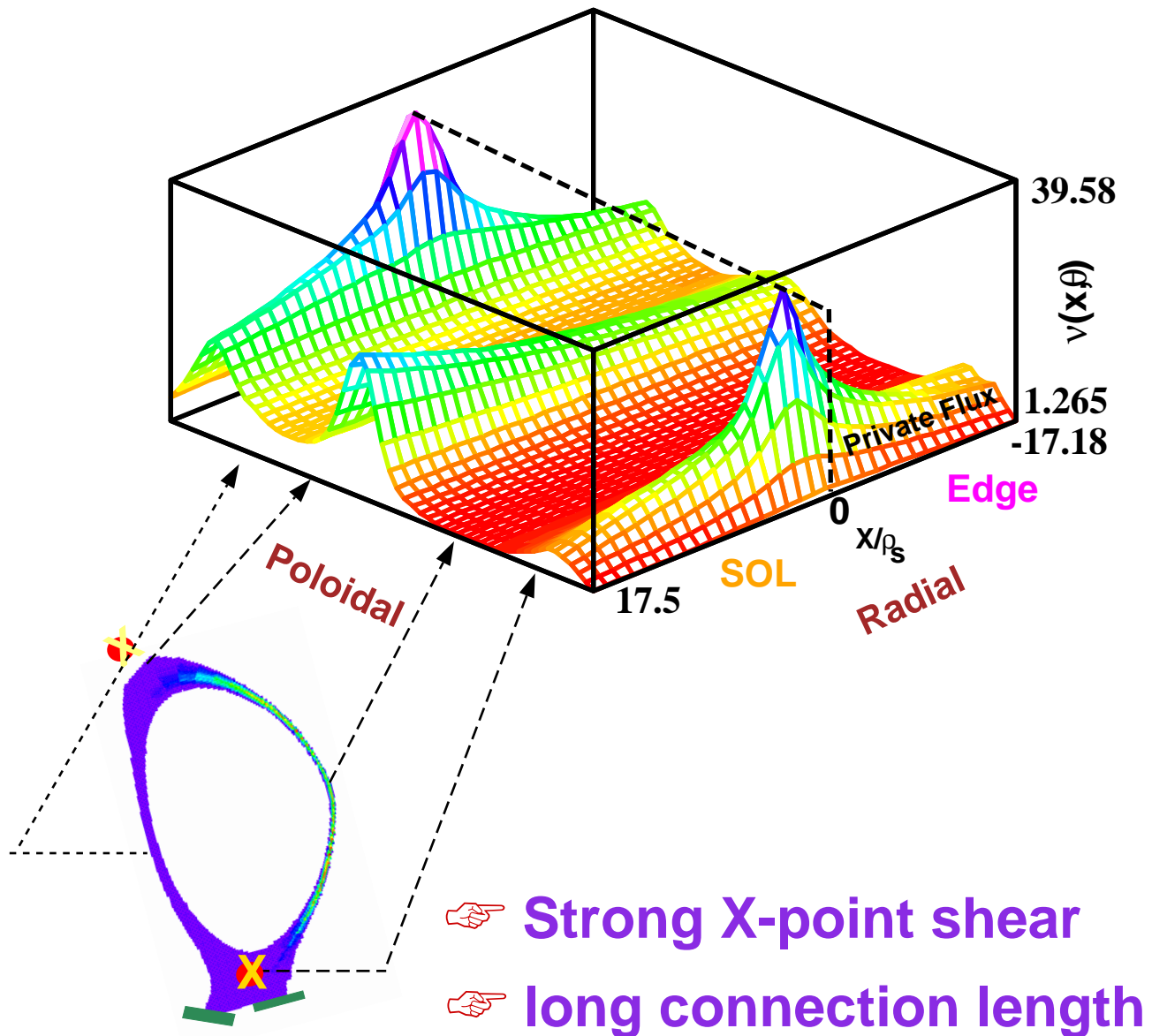
- Boundary Plasma Turbulence has a different characters than in the core and play an important role in core confinement
- BOUT is an unique code to simulate boundary plasma turbulence in a complex geometry
 - Observed large velocity shear layer
 - Proximity of open+closed flux surface
 - Presence of X-point
- BOUT is being applied to DIII-D, C-mod, NSTX, ITER for Snowmass, ...



Local Safety Factor, $v(\psi, \theta)$, has strong variations near X-points that affect mode



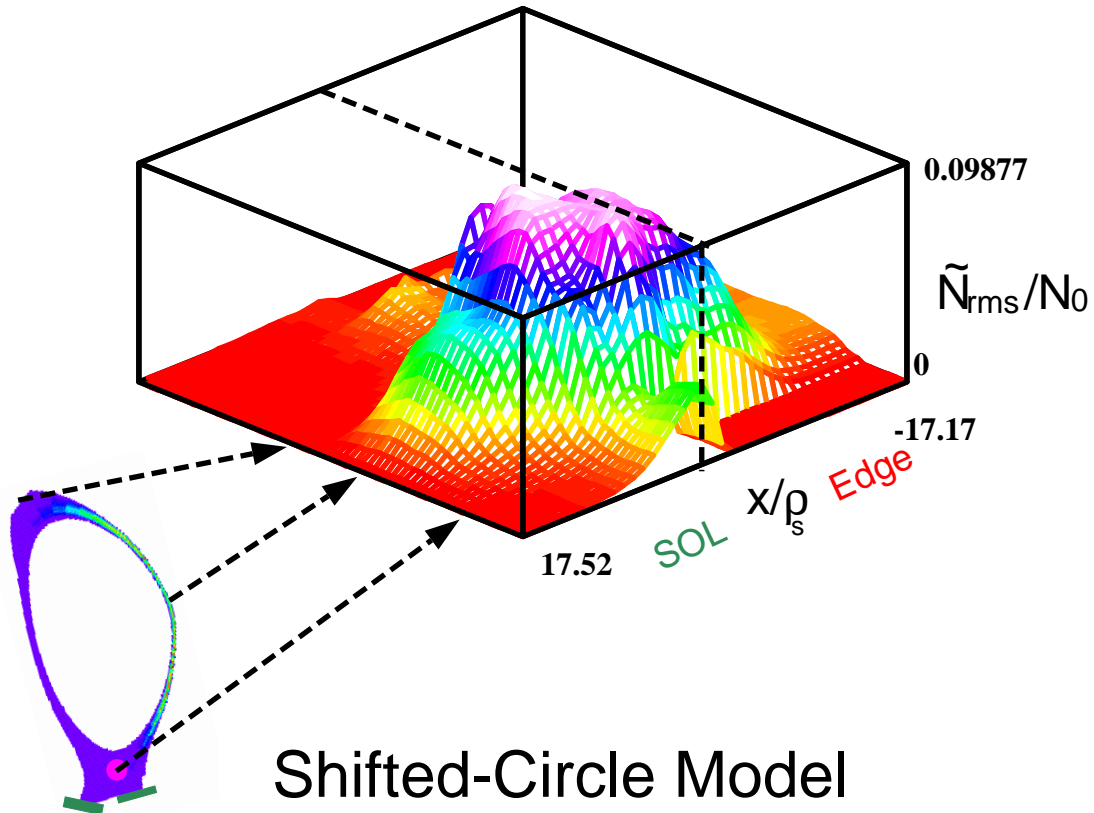
$$v(\psi, \theta) = a_{\text{eff}} B t / (R B_p)$$



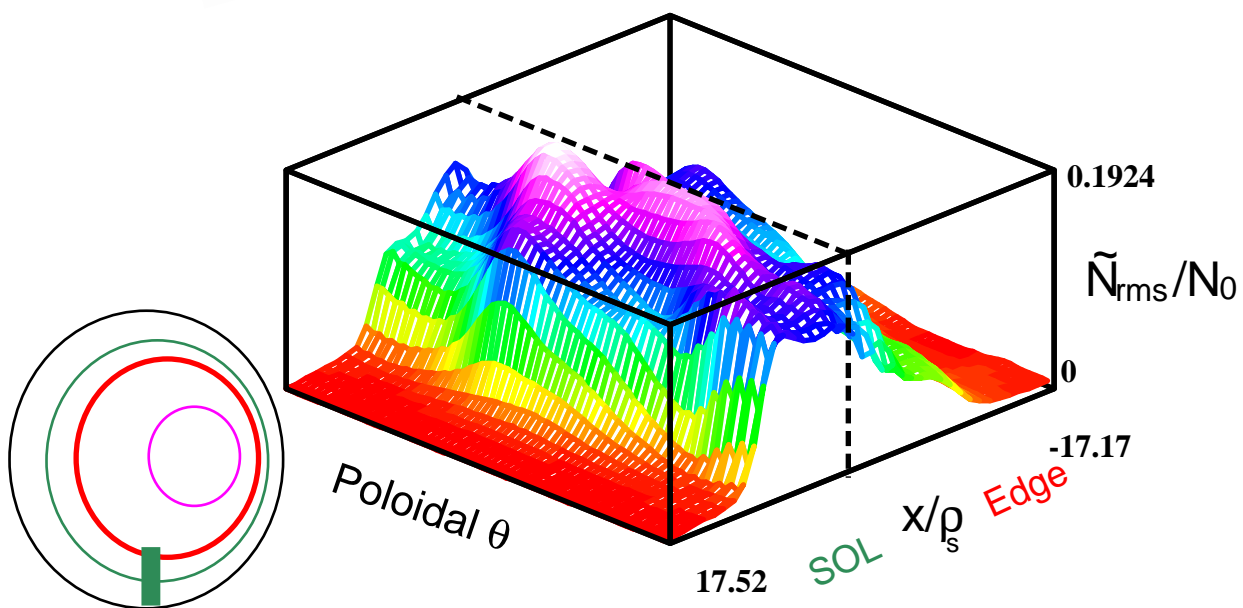
Density fluctuation is ballooning for X-point geom. vs. flute for shifted-circle



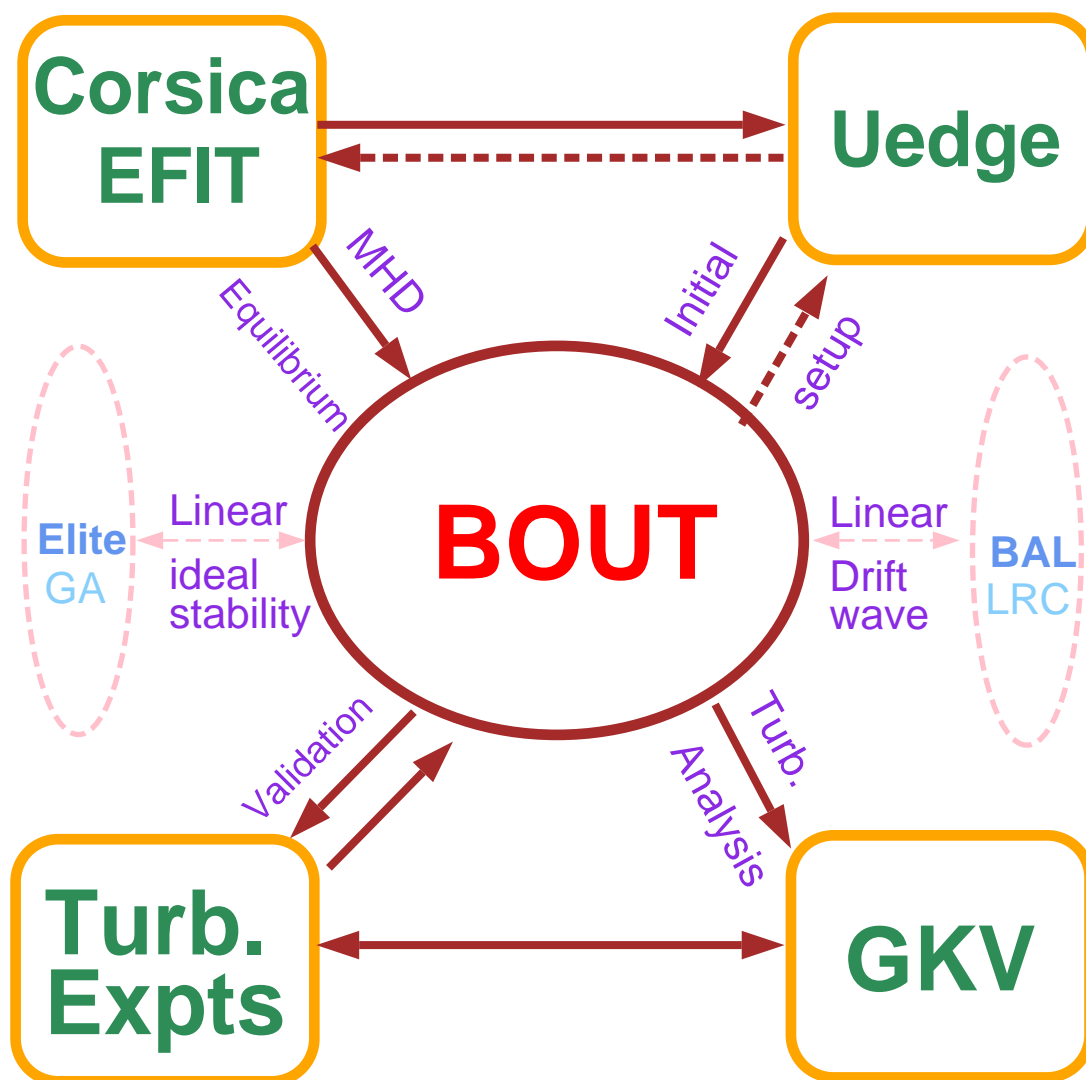
X-Point Model



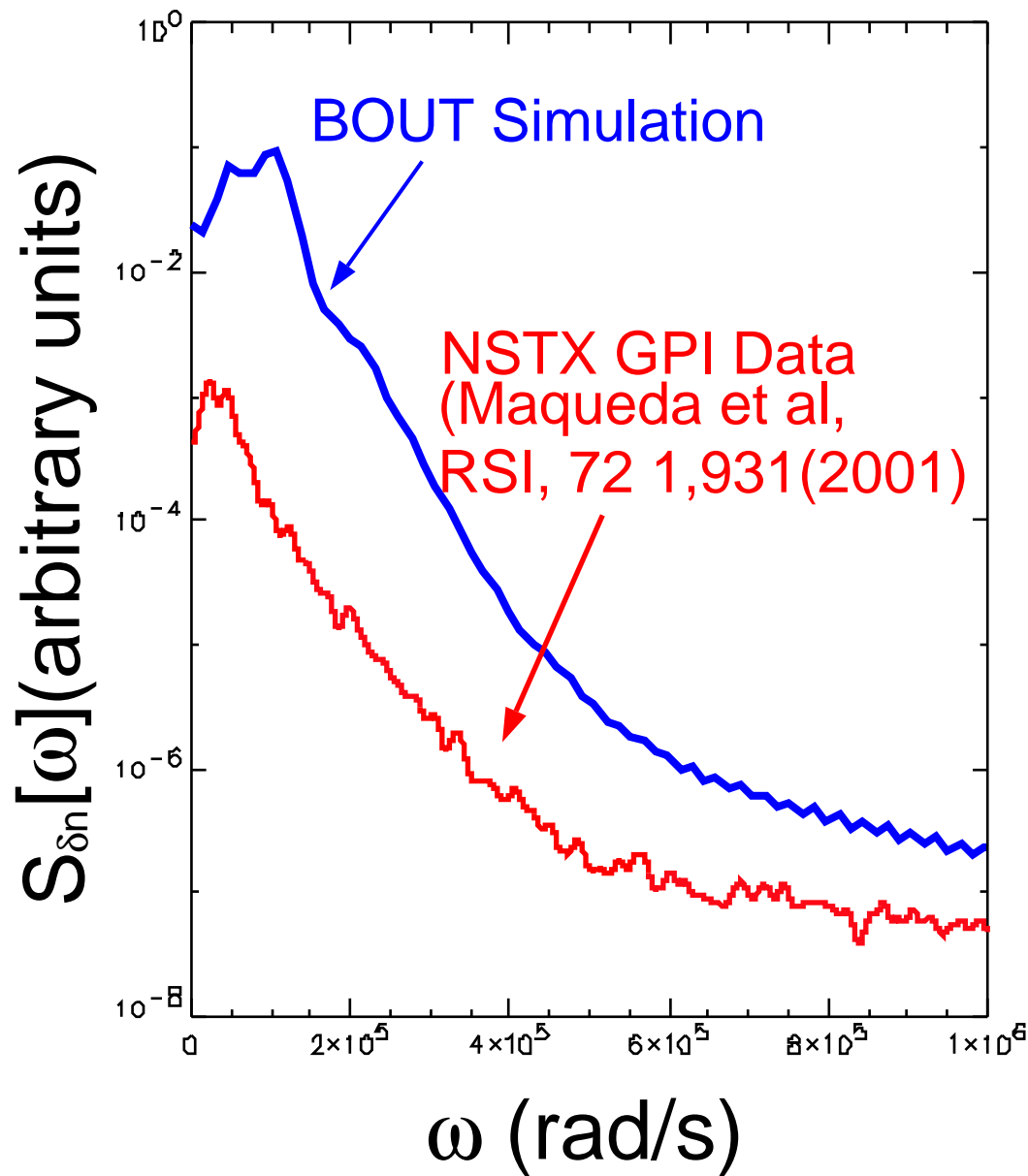
Shifted-Circle Model



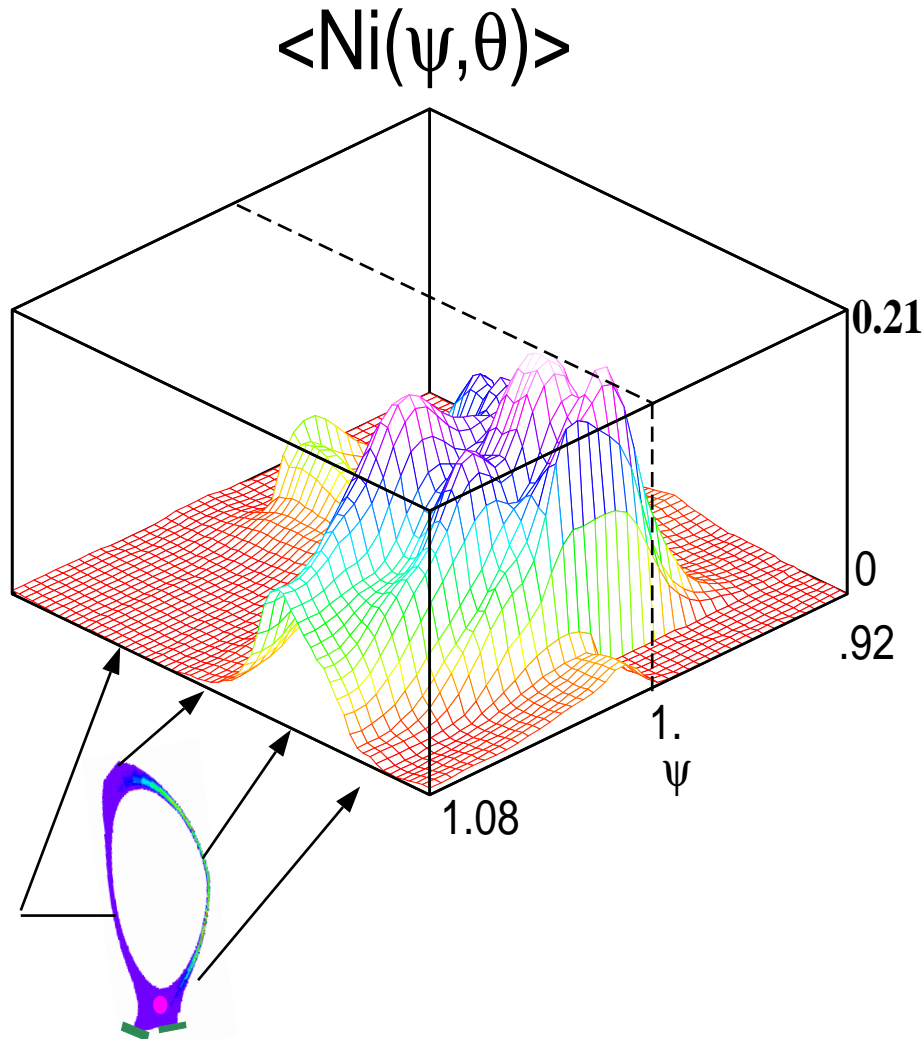
A suite of the codes work together
to make BOUT simulation results
similar to real experiments



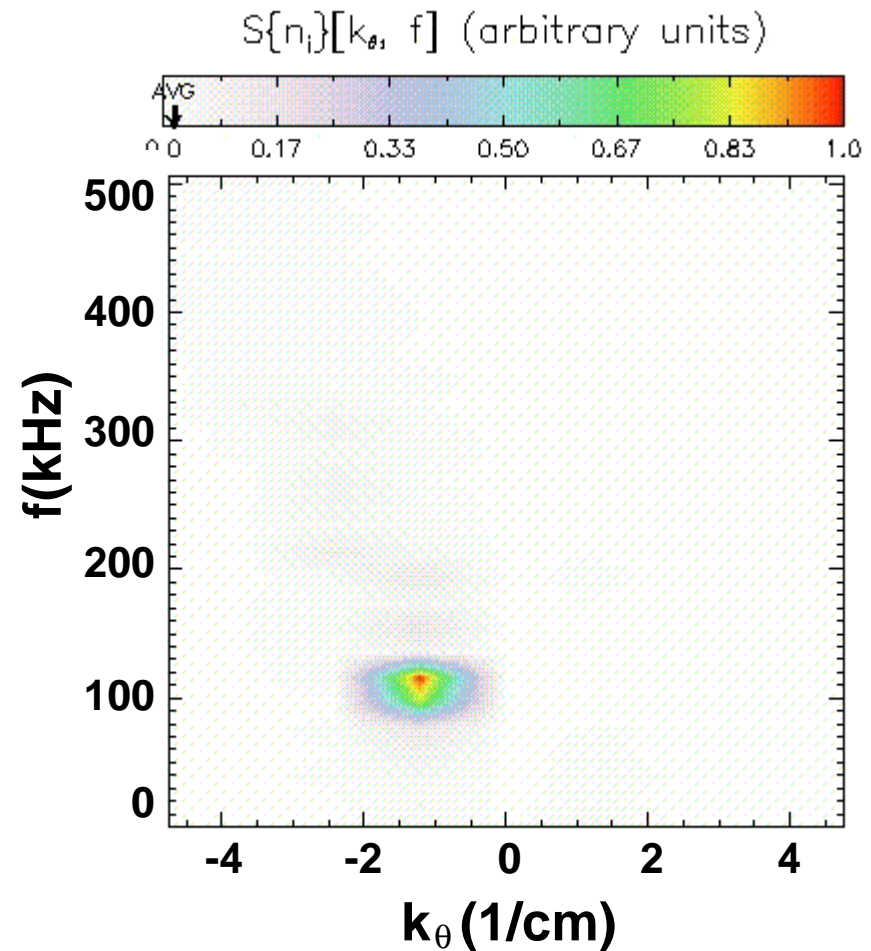
BOUT shows similar frequency spectrum as Gas Puff Image



BOUT Simulates Mode Similar to C-Mod Quasi-Coherent Mode



👉 Strong Dissipation near X-point
→ Resistive X-point Mode

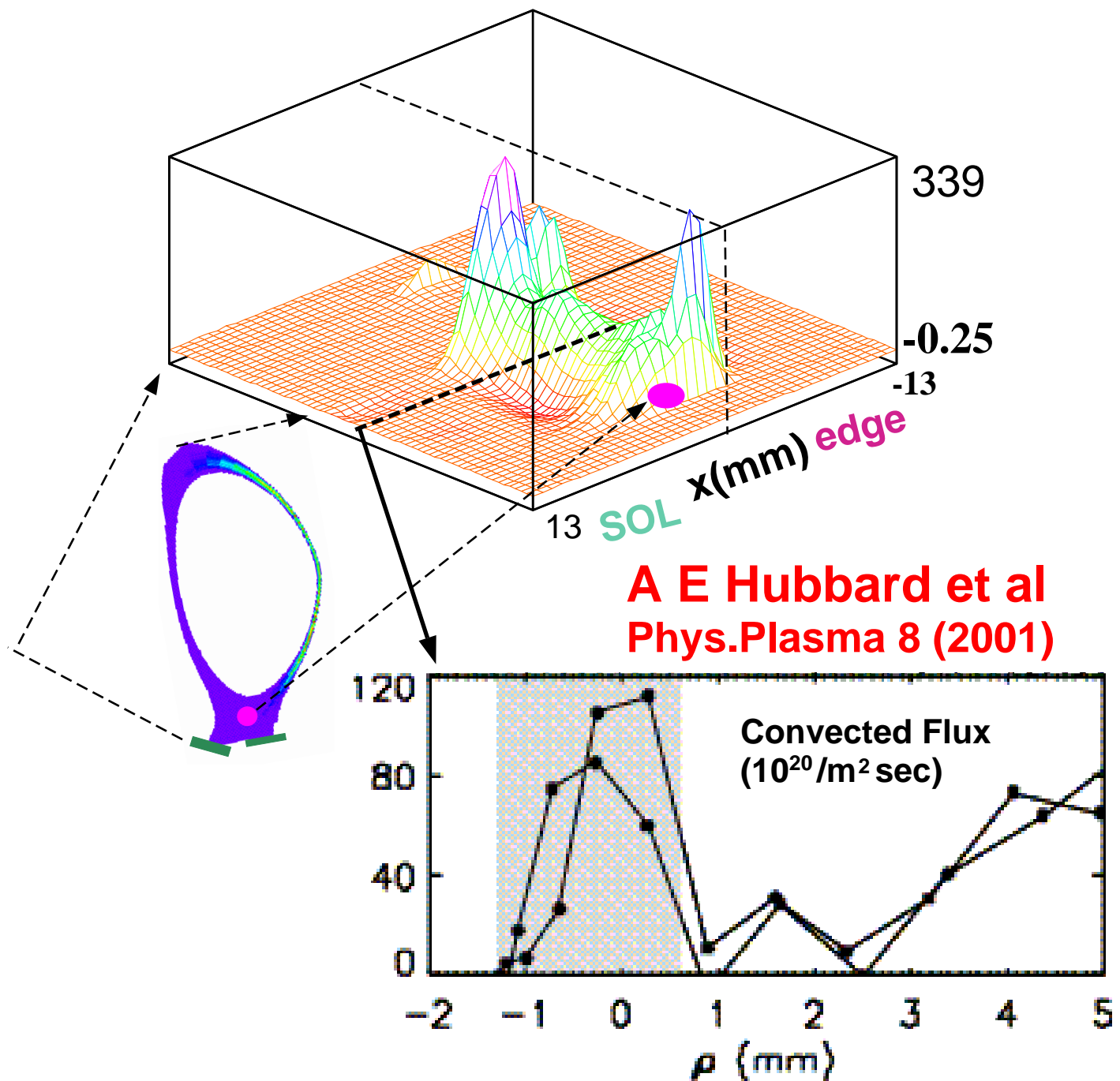


👉 Code Result well Localized
in f and k_θ resembles PCI
measurements

Particle Flux Γ_ψ is consistent with probe measurement near midplane region

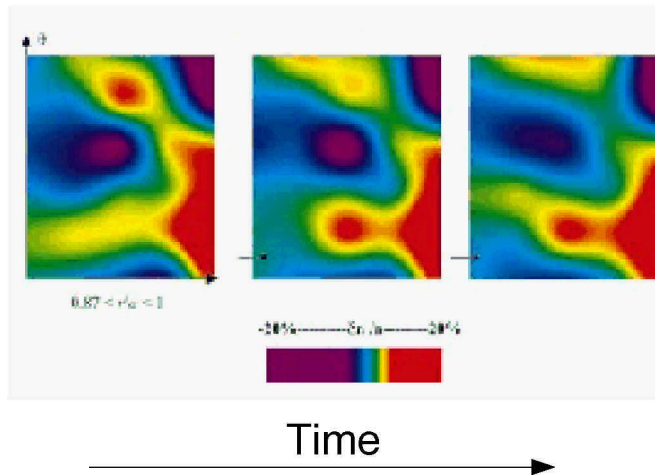


$$\Gamma_\psi = \langle \delta n \delta v_\psi \rangle (x 10^{20} / \text{m}^2 \text{ s})$$

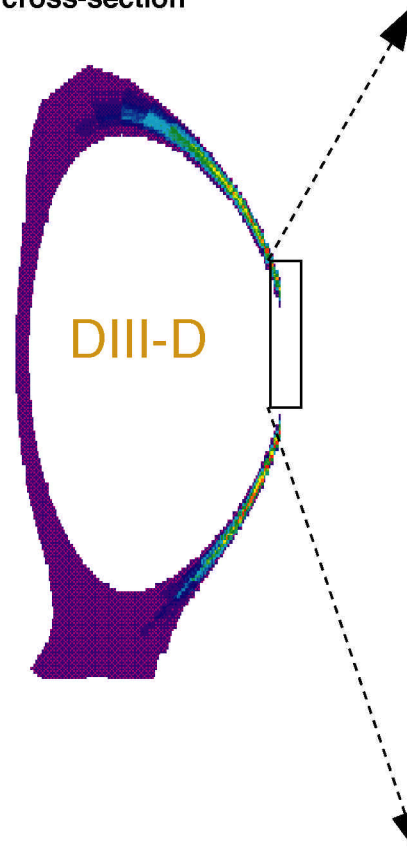


L-Mode Edge Turbulence in DIII-D

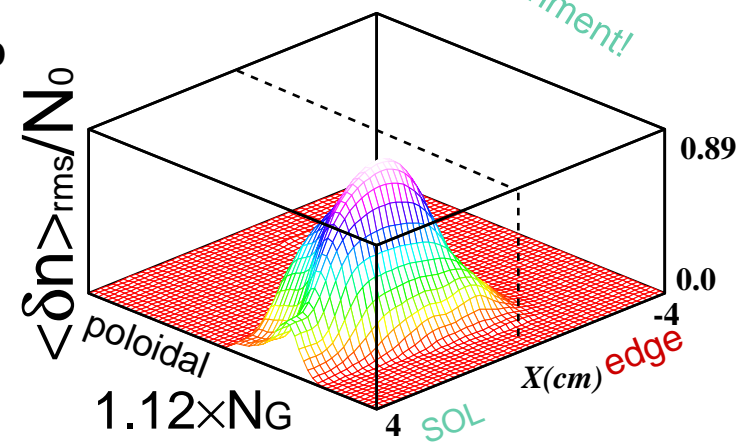
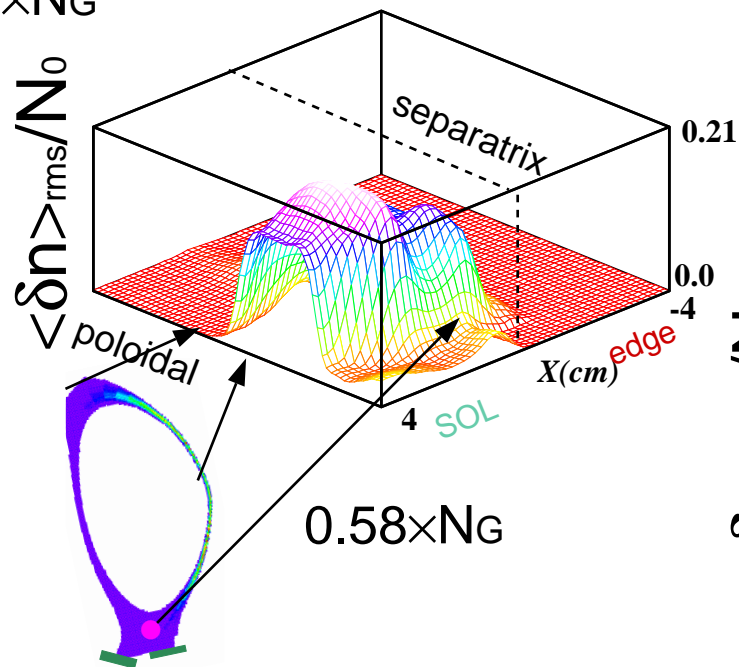
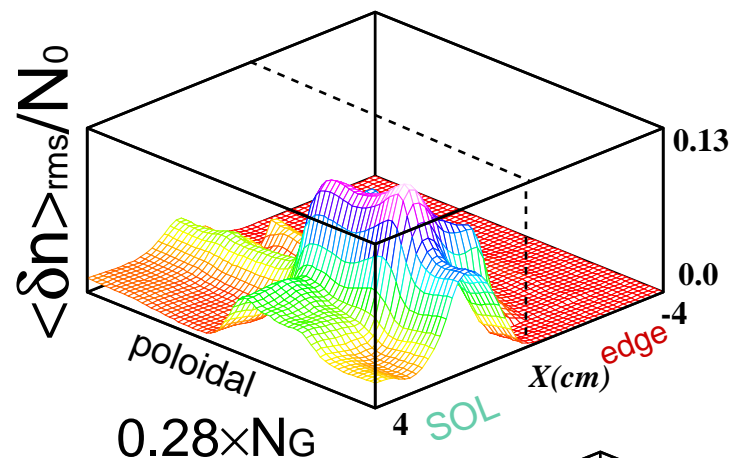
BES Expt.



Full poloidal
cross-section



Density Limit: High collisionality \Rightarrow fluctuation level/transport \uparrow and parallel correlation length \downarrow

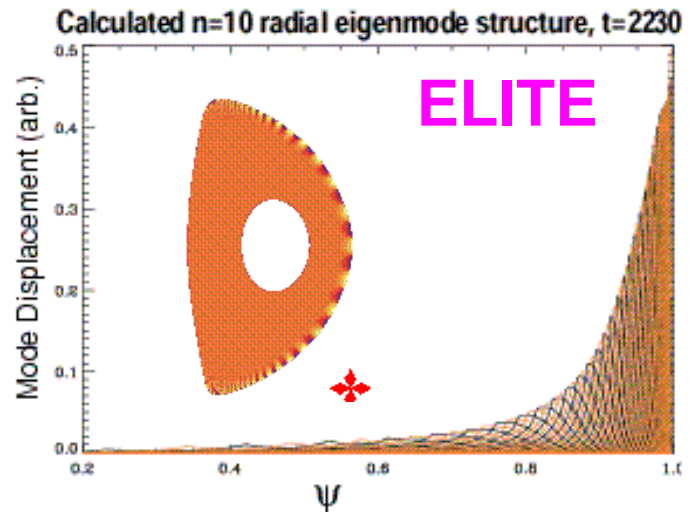
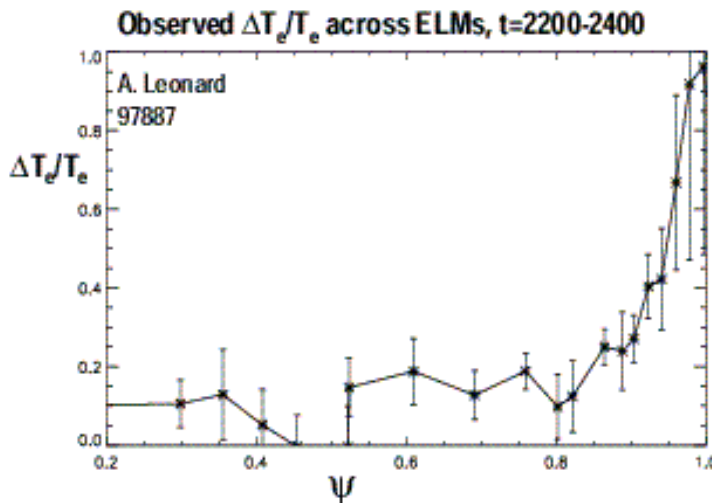


Drift wave \rightarrow Resistive MHD \rightarrow Detach \rightarrow Disruption

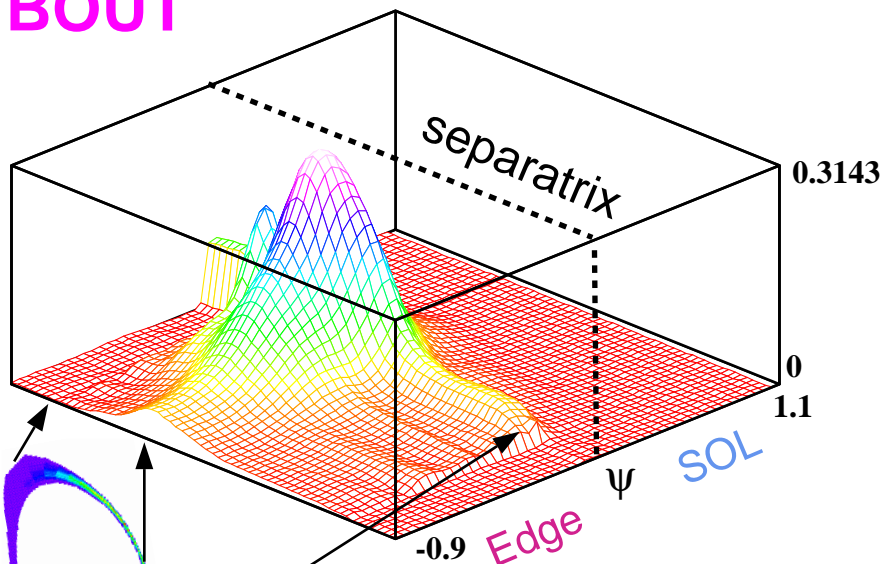
Density \uparrow with $P = \text{const.}$

Loss of balance between \perp and \parallel transport \Rightarrow detachment!

Calculated Mode Structure from BOUT and ELITE Consistent with Observed DIII-D ELM Depth



BOUT

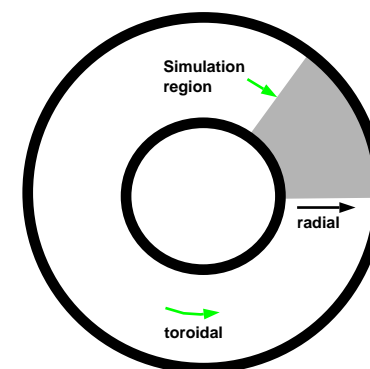
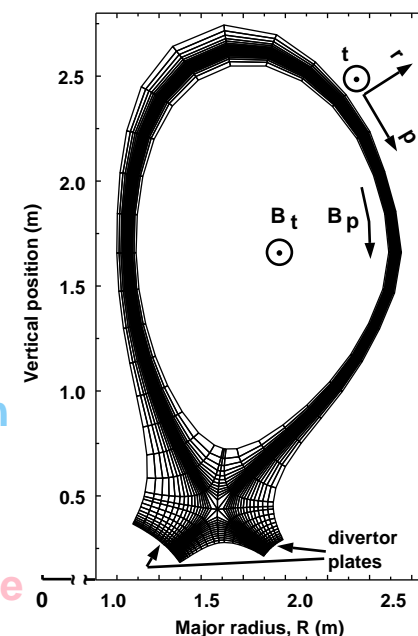


➡ Further support for predicted mode structure provided by divertor balance experiment (T.Petrie): ELM signals absent on high field side for double-null

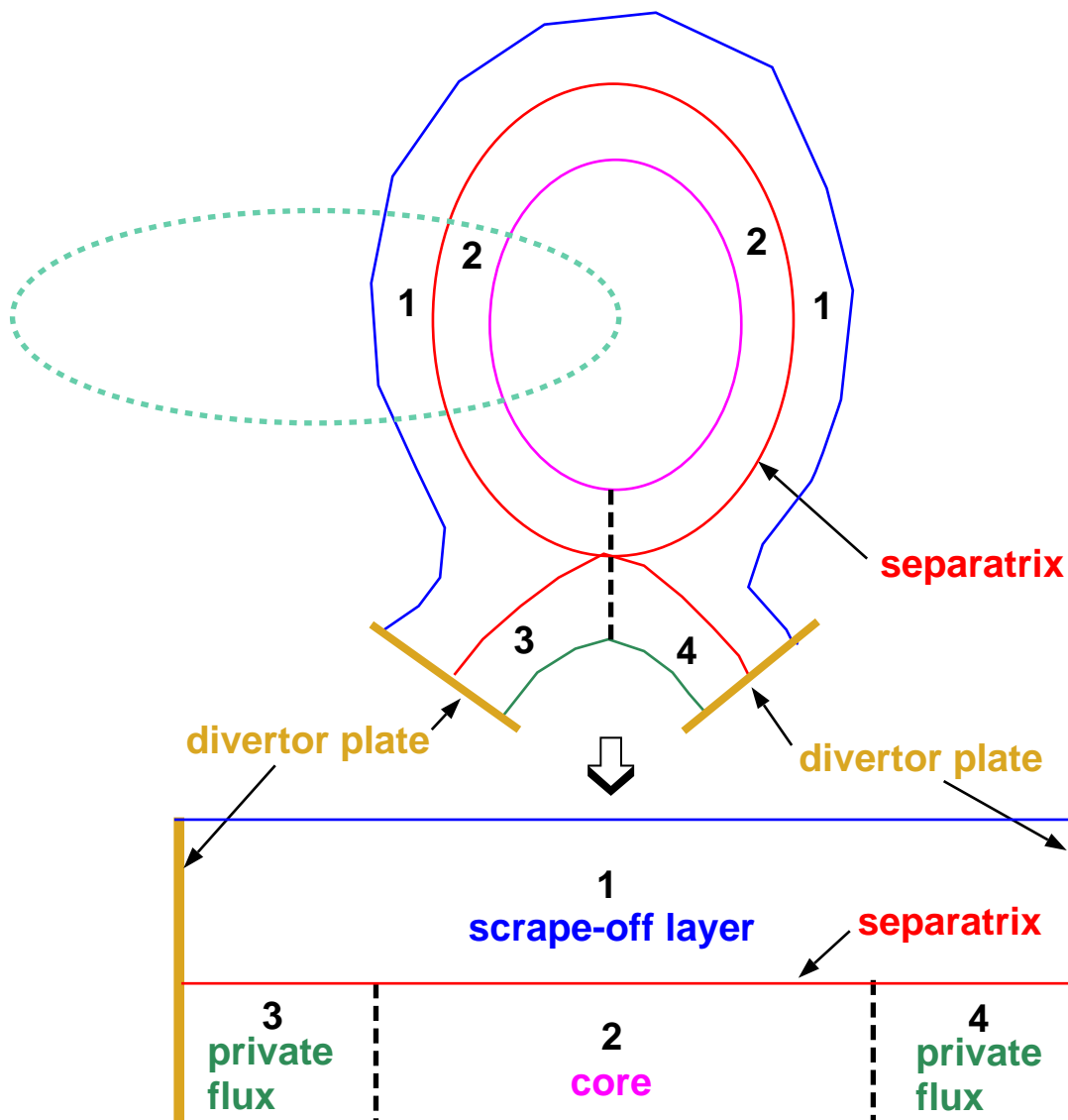
BOUT is a parallelized 3D nonlocal electromagnetic turbulence code using MPI



- ❖ The BOUT code solves for the plasma fluid equations in a 3-D toroidal segment.
- ❖ BOUT uses a fully implicit Newton-Krylov solver PVOE.
- ❖ BOUT is a parallelized code based on domain decomposition that uses the MPI system.
- ❖ BOUT has been tested on Linux PC clusters, Sun and DEC workstation clusters, and on the NERSC IBM SP and Cray-T3E.
- ❖ Parallel for one direction; parallelization in second direction is under way, will use ~1000---10000 PEs
- ❖ Mflop/s rates achieved is typically ~ 5---10% on IBM SP



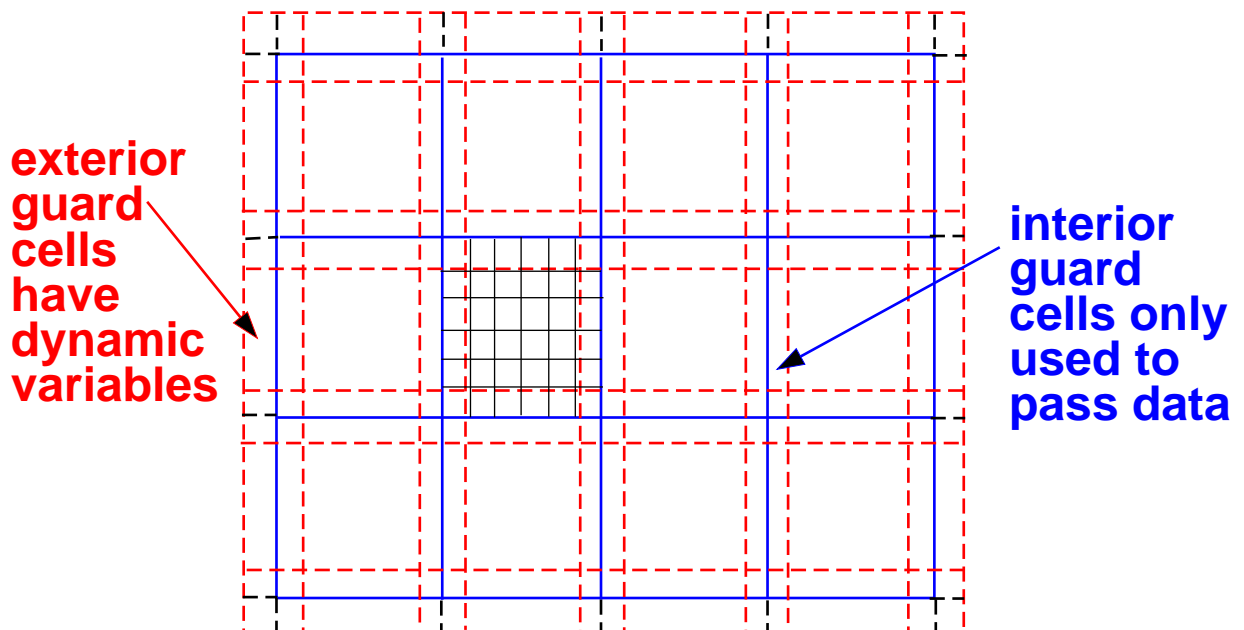
The poloidal plane is divided into four main regions for the domain decomposition model



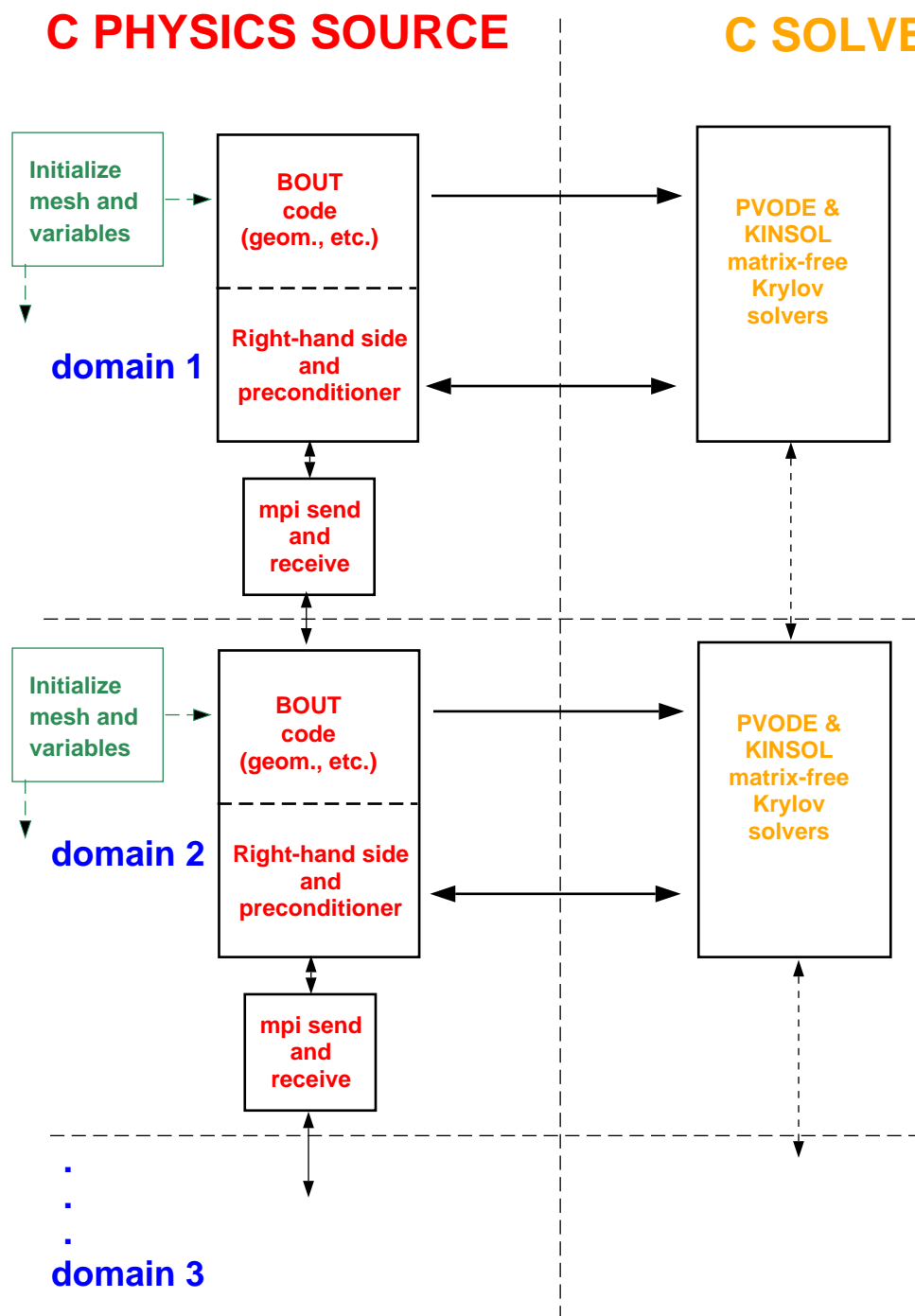
Each of four main regions can be further subdivided for the domain decomposition model



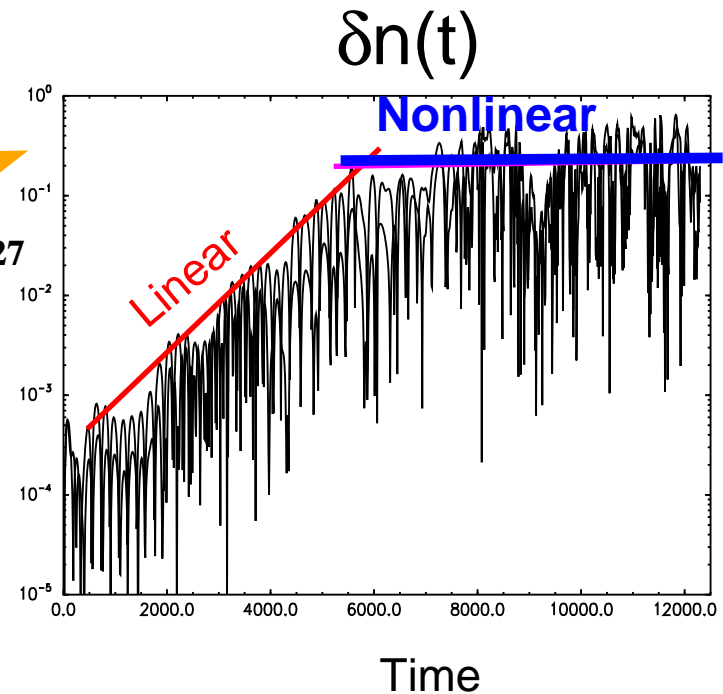
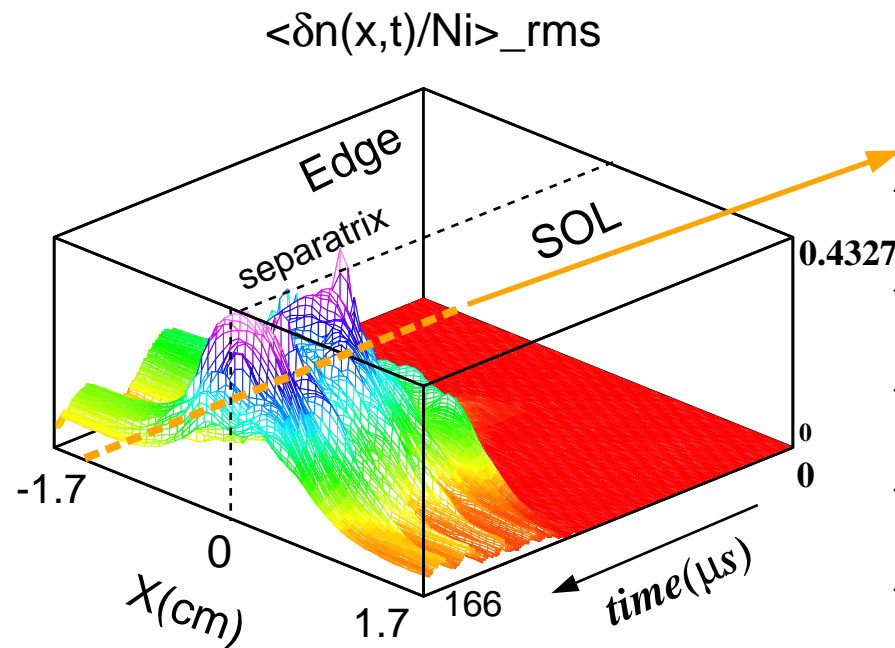
12	13	14	15
8	9	10	11
4	5	6	7
0 PF	1 CORE	2	PF ₃



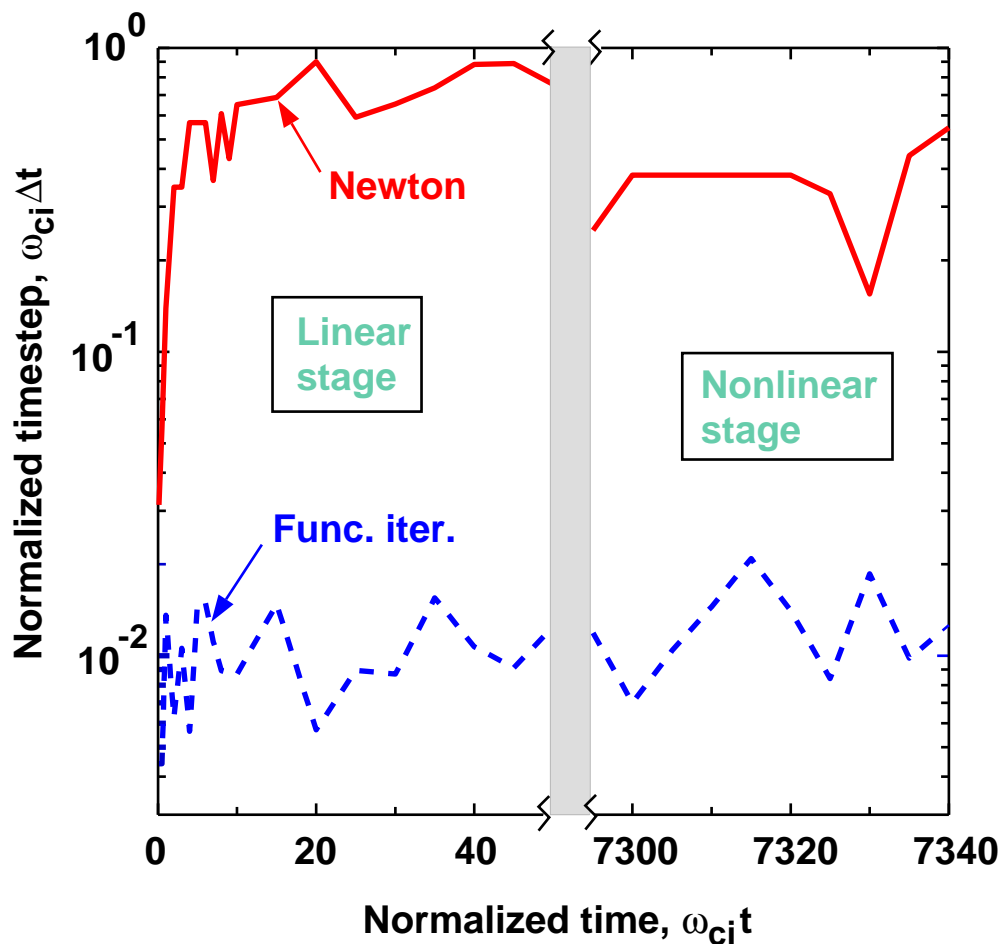
Schematic showing the two major components of parallel BOUT Code as replicated on each domain processor



Time history of linear growth and turbulence saturation



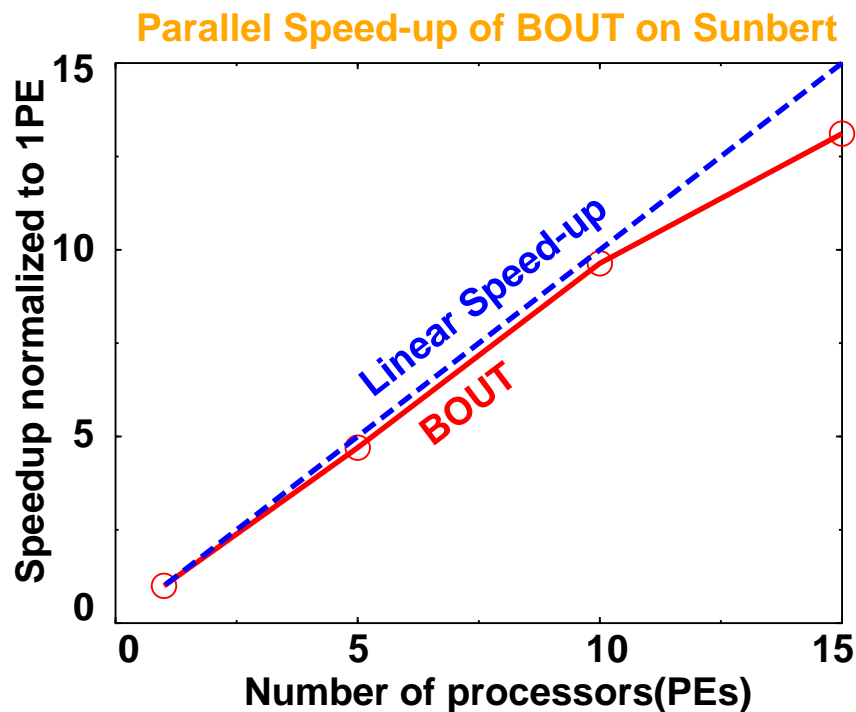
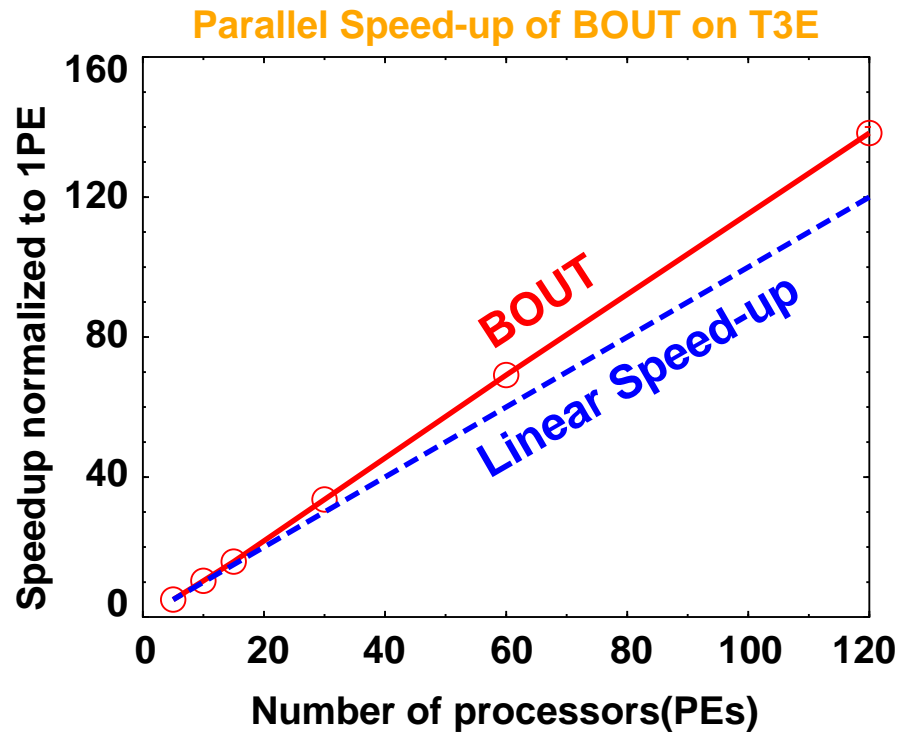
Time step showed in BOUT over the course of a time-dependent simulation showing improvement with Krylov vs. func. iter.



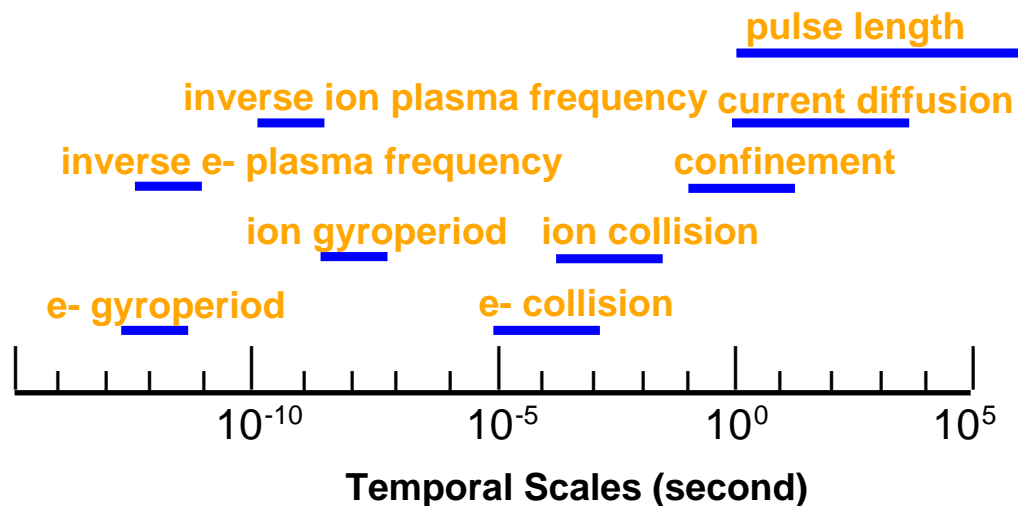
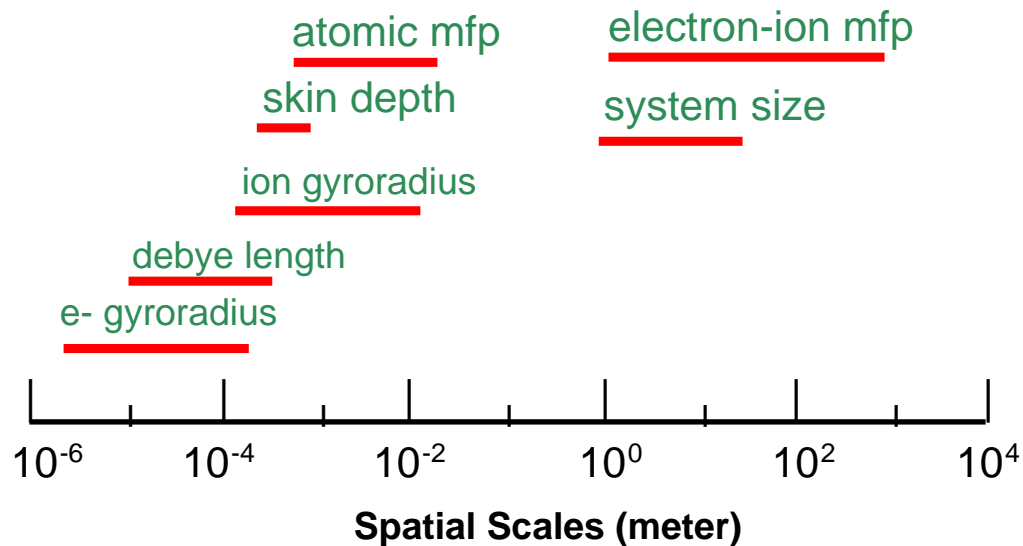
Comparison of Adams Predictor-Corrector and Newton-Krylov (BDF) Statistics in Linear Stage of the Simulation

Method	Number of RHS evaluations	Number of time steps	Average $\Omega_{ci}\Delta t$	Observed Δt order
One-step P/C	6212	5756	0.01	1
BDF Newton	1091	115	0.7	3-4

BOUT results show an almost linear speedup on T3E and Sunbert

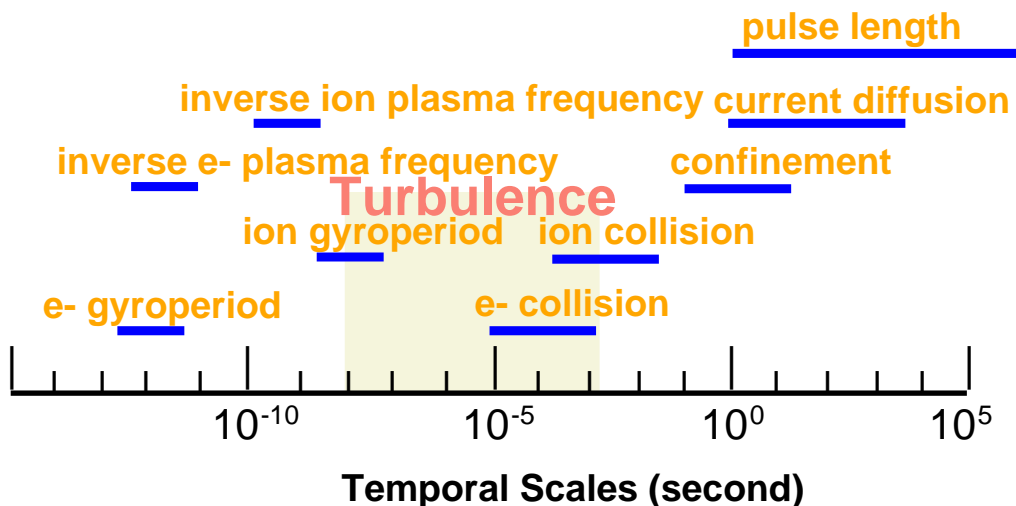
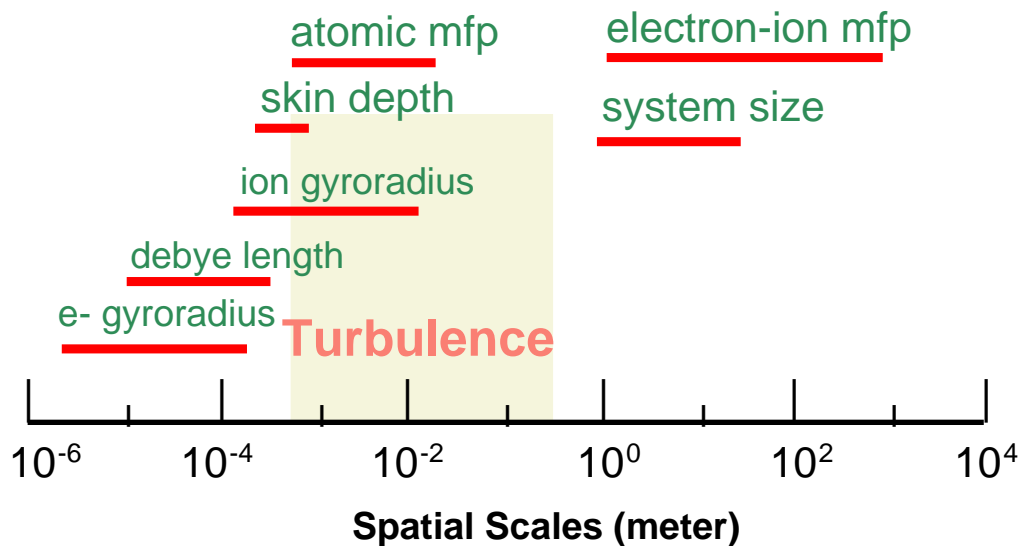


Huge range of spatial and temporal scales is a challenge to theory and simulations



Overlap in scales often means that strong theoretical ordering is not possible

BOUT simulates only part of boundary problems---Turbulence



It is even not possible to simulate whole boundary physics yet on today machines

BlueGene/L will provide enough computing power to simulate boundary physics



A proposed Kinetic BOUT code: 2V3D

- ➡ Resolution $30 \times 30 \times 100 \times 100 \times 1000 \sim 10^{10}$,
 $\Delta x \sim 1\text{mm}$, ion gyroradius spatial scale,
 $\Delta t \sim 10^{-8}$ second, Alfvén time scale
- ➡ Time $\sim 10 \text{ --- } 100 \text{ ms}$,
Thus number of timestep $\sim 1 \times 10^6 \text{ --- } 1 \times 10^7$
- ➡ Number of operation/grid point/step ~ 1000
- ➡ Total operations count to carry out the simulations $\sim 10^{19} \text{ --- } 10^{20}$
- ➡ With a 100 TF machine, the time required
 $\sim 10^{19} \text{ --- } 10^{20} / (10^{14} \times 3600) \sim 30 \text{ --- } 300 \text{ hours}$

Issues of BOUT performance on BlueGene/L



⌘ The division of work for BOUT on IBM SP ~ 100 PEs:

- 80% for evaluating the BOUT physics equations,
- 1% for I/O,
 - ⇒ a pointer variable is set so that each processor only reads a subset of the data needed for its domain.
 - ⇒ each processor writes and reads its own dump file for the data in its domain for restarting the problem.
- 12% for internal PVODE calculations,
- 6% for interprocessor MPI communications,
- 1% for other overhead costs,
- 1% variation for the load balance among processors.

⌘ We anticipate use ~10000 PEs on BlueGene/L,

- ~ a flux tube per PE
- Issues:
 - Parallel I/O:
 - Communications: Latence & bandwidth
 - File management: ~1000-10000 files per simulation
 - Storage: ~ 1TB of data per simulation
 - Unknown: